INDIAN INSTITUTE OF INFORMATION TECHNOLOGY DESIGN AND MANUFACTURING (IIITDM) KANCHEEPURAM

INTRODUCTION OF NEW COURSE

Course Title	Machining dynamics and adaptive control	Course Code	ME xxxx				
Dept./ Specialization	Mechanical Engineering	Structure (LTPC)	3	1	0	4	
To be offered for	UG/PG	Status	Core	1	Elect	tive 🔳	
Faculty Proposing the course	Dr. Kashfull Orra	Туре	New		Modification		
Recommendation from	ecommendation from the DAC: Yes Date of DAC		01-06-2021				
External Expert(s)	Prof. S. K. Choudhury, Depa	rtment of Mechan	ical Engineering IIT Kanpur				
Pre-requisite	Manufacturing process I and II	Submitted for ap	proval		46 th 5	46 th Senate	
Learning Objectives	metal cutting: turnin To analyse chatter cutting. To introduce the u	metal cutting: turning, milling and drilling operations. To analyse chatter and stability in machining dynamics and vibration of metal cutting.					
Learning Outcomes	 At the end of the course, the students will gain fundamentals of machining on orthogonal cutting and oblique cutting. The theoretical model will help the students to solve machining vibration problem accurately, will develop analytical skills to tackle the research related problems. They will have the ability for designing and analyzing adaptive control systems in the machining process, will have the ability to implement the adaptive control system for industrial use. 						
Contents of the course (With approximate break-up of hours for L/T/P)	cutting force, Shear angle. Of cutting forces. Mechanics breakage. (10 L + 3 T) Machining dynamics and vibrations, regenerative effeanalysis in orthogonal cutt stability in turning operation drilling operation-dynamics delay model, Frequency and Modal analysis: Introduc Identification of modal paran Numerical methods and com Adaptive Control: Models Laplace transformation, Traninput single output systems control system-direct and in design of on-line parameter.	ting process and modelling: Orthogonal cutting-Mechanistic modelling of force, Shear angle. Oblique cutting-cutting geometry and parameters, prediction ag forces. Mechanics of turning, milling and drilling process, Tool wear and Tool et. (10 L + 3 T) ting dynamics and vibration: Fundamentals of free, forced and self-excited ans, regenerative effect in 1-DOF, mode coupling effect in 2-DOF. Stability in orthogonal cutting-regenerative chatter vibration, stability lobe diagram, in turning operation. Analytical prediction of chatter vibration in milling and operation-dynamics of milling model, dynamics of drilling force model, Time model, Frequency and time domain stability solution. (12 L + 4 T) analysis: Introduction to modal analysis, Frequency response function, cation of modal parameters, modal analysis for multi-degree-of-freedom systems, cal methods and computational dynamics of modal analysis. (8 L + 3 T) ve Control: Models for dynamic systems-open loop and closed loop systems, transformation, Transfer functions, Review of control design concepts for single ingle output systems, Extension to multi-input multi-output systems. Adaptive system-direct and indirect adaptive control, model reference adaptive control, of on-line parameter estimators. Design formulations using state-space and cy domain, Stability analysis in feedback controls using Lyapunov function,					

	solving. (12 L + 4 T)
Text Book	1. A. Bhattacharyya, Metal cutting: Theory and Practice, 8 th Ed. New Central
	Book Agency (P) Ltd, 2012.
	2. P.A. Ioannou and J. Sun, Robust Adaptive control, 1 st Ed. 1995
Reference Books	1. K.Ogata, Modrern Cpntrol Engineering, 4 th Ed. Pearson Education Int. 2002